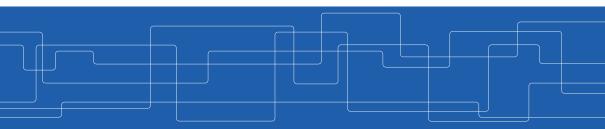


Processes Synchronization - Part II

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Deadlocks



Multiprogramming environment: several processes compete for a finite number of resources.



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- Multiprogramming environment: several processes compete for a finite number of resources.
- ► A process requests resources: if the resources are not available at that time, the process enters a waiting state.
- What if the requests resources are held by other waiting processes?
- This situation is called a deadlock.



System consists of *m* resources: R_1, R_2, \cdots, R_m



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- ▶ Resource types: CPU cycles, memory space, I/O devices



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- System consists of *m* resources: R_1, R_2, \cdots, R_m
- ► Resource types: CPU cycles, memory space, I/O devices
- Each resource type R_i has W_i instances.
- Each process utilizes a resource as follows:
 - Request
 - Use
 - Release



Deadlock Characterization (1/3)

- Deadlock can arise if four conditions hold simultaneously:
 - Mutual exclusion
 - Hold and wait
 - No preemption
 - Circular wait



Deadlock Characterization (2/3)

- Mutual exclusion
 - Only one process at a time can use a resource.



Deadlock Characterization (2/3)

Mutual exclusion

• Only one process at a time can use a resource.

Hold and wait

• A process holding at least one resource is waiting to acquire additional resources held by other processes.



Deadlock Characterization (3/3)

► No preemption

• A resource can be released only voluntarily by the process holding it, after that process has completed its task.



Deadlock Characterization (3/3)

► No preemption

• A resource can be released only voluntarily by the process holding it, after that process has completed its task.

Circular wait

- A set processes: $\{P_0, P_1, \cdots, P_n\}$
- P_0 is waiting for a resource that is held by P_1
- P_1 is waiting for a resource that is held by P_2
- ...
- P_n is waiting for a resource that is held by P_0



Deadlock Example (1/2)

/* Create and initialize the mutex locks */
pthread_mutex_t first_mutex;
pthread_mutex_t second_mutex;

pthread_mutex_init(&first_mutex, NULL);
pthread_mutex_init(&second_mutex, NULL);



Deadlock Example (2/2)

```
void *thread_one(void *args) {
   pthread_mutex_lock(&first_mutex);
   pthread_mutex_lock(&second_mutex);
   // do some work
   pthread_mutex_unlock(&second_mutex);
   pthread_mutex_unlock(&first_mutex);
```

```
pthread_exit(0);
```



Deadlock Example (2/2)

```
void *thread_one(void *args) {
   pthread_mutex_lock(&first_mutex);
   pthread_mutex_lock(&second_mutex);
   // do some work
   pthread_mutex_unlock(&second_mutex);
   pthread_mutex_unlock(&first_mutex);
```

```
pthread_exit(0);
```

```
void *thread_two(void *args) {
   pthread_mutex_lock(&second_mutex);
   pthread_mutex_lock(&first_mutex);
   // do some work
   pthread_mutex_unlock(&first_mutex);
   pthread_mutex_unlock(&second_mutex);
   pthread_exit(0);
```





Resource-Allocation Graph



• A set of vertices V and a set of edges E.



► A set of vertices *V* and a set of edges *E*.

Vertices

- All the processes in the system: $P = P_1, P_2, \cdots, P_n$
- All resource types in the system: $R = R_1, R_2, \cdots, R_m$



► A set of vertices *V* and a set of edges *E*.

Vertices

- All the processes in the system: $P = P_1, P_2, \cdots, P_n$
- All resource types in the system: $R = R_1, R_2, \cdots, R_m$

Edges

- Request edge: directed edge $P_i \rightarrow R_j$
- Assignment edge: directed edge $R_j \rightarrow P_i$



Process (vertices)





Process (vertices)



Resource type with 4 instances (vertices)





Process (vertices)

• Resource type with 4 instances (vertices)

• P_i requests instance of R_j (edge)





Process (vertices)

Resource type with 4 instances (vertices)

• P_i requests instance of R_j (edge)

• P_i is holding an instance of R_j (edge)





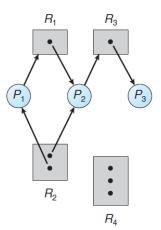






Resource-Allocation Graph Example (1/3)

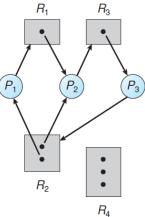
• Example of a resource allocation graph.





Resource-Allocation Graph Example (2/3)

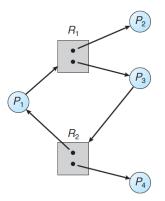
Resource allocation graph with a deadlock.





Resource-Allocation Graph Example (3/3)

• Resource allocation graph with a cycle but no deadlock.





- ► If graph contains no cycles
 - No deadlock



- ► If graph contains no cycles
 - No deadlock
- ► If graph contains a cycle
 - If only one instance per resource type, then deadlock.
 - If several instances per resource type, possibility of deadlock.



• Ensure that the system will never enter a deadlock state:



- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance



- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance
- ► Allow the system to enter a deadlock state and then recover.



- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance
- ► Allow the system to enter a deadlock state and then recover.
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems.



Deadlock Prevention



• Deadlock can arise if four conditions hold simultaneously:

- Mutual exclusion
- Hold and wait
- No preemption
- Circular wait



• Deadlock can arise if four conditions hold simultaneously:

- Mutual exclusion
- Hold and wait
- No preemption
- Circular wait
- Restrain the ways requests can be made.



Mutual exclusion

- Not required for sharable resources, e.g., read-only files.
- Must hold for non-sharable resources.



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- Solution 2: allows a process to request resources only when it has none.



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Hold and wait

- Must guarantee that whenever a process requests a resource, it does not hold any other resources.
- Solution 1: require a process to request and be allocated all its resources before it begins execution.
- Solution 2: allows a process to request resources only when it has none.
- Low resource utilization
- Starvation possible



► No preemption



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• If a process that is holding some resources, requests another resource that cannot be immediately allocated to it, then all resources currently being held are released.



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- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting.

Circular wait

• Impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration.

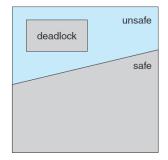


Deadlock Avoidance



► If a system is in the safe state

• No deadlock

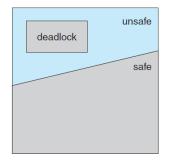




► If a system is in the safe state

No deadlock

- ▶ If a system is in the unsafe state
 - Possibility of deadlock

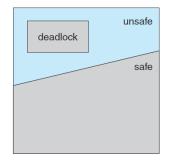




► If a system is in the safe state

No deadlock

- ▶ If a system is in the unsafe state
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Avoidance

• Ensure that a system will never enter an unsafe state.



Safe State (1/2)

When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state.



Safe State (1/2)

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state.
- Safe state: there exists a sequence ⟨P₁, P₂, · · · , P_n⟩ of all the processes in the systems such that for each P_i, the resources that P_i can still request be satisfied by: currently available resources + resources held by all the P_i, with j < i.</p>



Safe State (2/2)

If P_i resource needs are not immediately available, then P_i can wait until all P_j have finished.

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Safe State (2/2)

- If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished.
- ▶ When *P_j* is finished, *P_i* can obtain needed resources, execute, return allocated resources, and terminate.
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on.



- ▶ 3 processes: P_0 through P_2
- ▶ 1 resource type:
 - A (12 instances)
- Snapshot at time T_0

	Maximum Needs	Current Needs
P_0	10	5
P_1	4	2
P_2	9	2



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► Safe mode sequence?



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- ► Snapshot at time *T*₀

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• Safe mode sequence? $\langle P_1, P_0, P_2 \rangle$



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Suppose that, at time T₁, process P₂ requests and is allocated one more resource.



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- Suppose that, at time T₁, process P₂ requests and is allocated one more resource.
- Safe mode sequence? Not safe



Avoidance Algorithms

- ► Single instance of a resource type
 - Use a resource-allocation graph



Avoidance Algorithms

- ► Single instance of a resource type
 - Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the banker's algorithm



Resource-Allocation Graph Algorithm





► Claim edge P_i → R_j: indicates that process P_i may request resource R_j; represented by a dashed line



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- ► Claim edge P_i → R_j: indicates that process P_i may request resource R_j; represented by a dashed line
- ► Claim edge converts to request edge when a process requests a resource.
- Request edge converted to an assignment edge when the resource is allocated to the process.



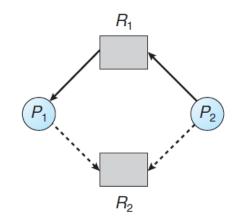
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- ► Claim edge converts to request edge when a process requests a resource.
- Request edge converted to an assignment edge when the resource is allocated to the process.
- When a resource is released by a process, assignment edge reconverts to a claim edge.
- Resources must be claimed a priori in the system.

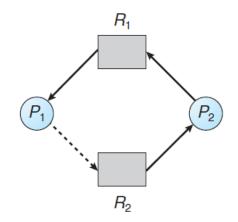


Resource-Allocation Graph





Unsafe State In Resource-Allocation Graph





Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_j .
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph.





Multiple instances



Multiple instances

• Each process must a priori claim of the maximum use.



Multiple instances

- Each process must a priori claim of the maximum use.
- ▶ When a process requests a resource it may have to wait.



Multiple instances

- Each process must a priori claim of the maximum use.
- ▶ When a process requests a resource it may have to wait.
- When a process gets all its resources, it must return them in a finite amount of time.



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- ► Available: vector of length m.
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- Max: $n \times m$ matrix.
 - If Max[i, j] = k, then process P_i may request at most k instances of resource type R_j.



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- ► *Max*: *n* × *m* matrix.
 - If Max[i, j] = k, then process P_i may request at most k instances of resource type R_j.
- ► Allocation: *n* × *m* matrix.
 - If Allocation[i, j] = k then P_i is currently allocated k instances of R_j .



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- ► Allocation: *n* × *m* matrix.
 - If Allocation[i, j] = k then P_i is currently allocated k instances of R_j .
- ► *Need*: *n* × *m* matrix.
 - If Need[i,j] = k, then P_i may need k more instances of R_j to complete its task Need[i,j] = Max[i,j] Allocation[i,j]



1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

Work = Available Finish[i] = false for $i = 0, 1, \dots n - 1$



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- 2. Find an *i* such that both:
 - 1. Finish[i] = false
 - 2. $Need_i \leq Work$

If no such i exists, go to step 4.



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 Work = Work + Allocation_i Finish[i] = true Go to step 2



 Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize: *Work* = *Available*

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- 2. Find an *i* such that both:
 - 1. Finish[i] = false
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If no such i exists, go to step 4.

- Work = Work + Allocation; Finish[i] = true Go to step 2
- 4. If Finish[i] == true for all *i*, then the system is in a safe state.



Resource-Request Algorithm for Process P_i (1/2)

► Request_i = request vector for process P_i. If Request_i[j] = k, then process P_i wants k instances of resource type R_j.



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- ► 1. If *Request_i* ≤ *Need_i*, go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim.
- ► 2. If *Request_i* ≤ *Available*, go to step 3. Otherwise *P_i* must wait, since resources are not available.



Resource-Request Algorithm for Process P_i (2/2)

► 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

 $Available = Available - Request_i$ $Allocation_i = Allocation_i + Request_i$ $Need_i = Need_i - Request_i$



Resource-Request Algorithm for Process P_i (2/2)

► 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

Available = Available - Request; Allocation; = Allocation; + Request;

 $Need_i = Need_i - Request_i$

• If safe: the resources are allocated to P_i



Resource-Request Algorithm for Process P_i (2/2)

► 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request_i

Allocation_i = Allocation_i + Request_i

Need_i = Need_i - Request_i
```

- If safe: the resources are allocated to P_i
- If unsafe: P_i must wait, and the old resource-allocation state is restored



- ▶ 5 processes: P_0 through P_4
- ► 3 resource types:
 - A (10 instances), B (5 instances), and C (7 instances)
- ► Snapshot at time *T*₀

	Allocation	Max	Available
	ABC	A B C	A B C
0	010	753	332
\mathcal{P}_1	200	322	
2	302	902	
3	211	222	
$^{-2}_{4}$	002	433	



► The content of the matrix *Need* is defined to be *Max* - *Allocation*

	Allocation	Max	Available		Need
	A B C	A B C	A B C		ABC
P_0	010	753	332	P_0	743
P_1	200	322		P_1	122
P_2	302	902		P_2	600
P_3	211	222		P_3	011
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► Is the system safe?



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P_2	302	902		P_2	600
P_3	211	222		P_3	$0\ 1\ 1$
P_4	002	433		P_4	431

▶ Is the system safe? $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria.



- ▶ *P*¹ Request (1, 0, 2)
- Check that $Request \leq Available: (1,0,2) \leq (3,3,2) \Rightarrow true$



- ► *P*₁ Request (1, 0, 2)
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► Executing safety algorithm shows that sequence (P₁, P₃, P₄, P₀, P₂) satisfies safety requirement.



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- Can request for (3, 3, 0) by P_4 be granted?



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- ► Executing safety algorithm shows that sequence (P₁, P₃, P₄, P₀, P₂) satisfies safety requirement.
- Can request for (3, 3, 0) by P_4 be granted?
- Can request for (0, 2, 0) by P_0 be granted?



Deadlock Detection



Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme



Single Instance of Each Resource Type

- ► Maintain wait-for graph.
 - Nodes are processes.
 - $P_i \rightarrow P_j$ if P_i is waiting for P_j .



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- ▶ Periodically invoke an algorithm that searches for a cycle in the graph.



Single Instance of Each Resource Type

- Maintain wait-for graph.
 - Nodes are processes.
 - $P_i \rightarrow P_j$ if P_i is waiting for P_j .
- ▶ Periodically invoke an algorithm that searches for a cycle in the graph.
- If there is a cycle, there exists a deadlock.

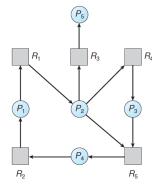


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 - Nodes are processes.
 - $P_i \rightarrow P_j$ if P_i is waiting for P_j .
- ▶ Periodically invoke an algorithm that searches for a cycle in the graph.
- If there is a cycle, there exists a deadlock.
- ► An algorithm to detect a cycle in a graph requires an O(n²) operations, where n is the number of vertices in the graph.



Resource-Allocation Graph and Wait-for Graph



Resource-allocation graph

 (P_5) (P_1) (P_2) (P_3) (P_4)

Corresponding Wait-for graph



Data Structures for Deadlock Detection

 Available: vector of length m, indicates the number of available resources of each type.



Data Structures for Deadlock Detection

- ► *Available*: vector of length *m*, indicates the number of available resources of each type.
- ► Allocation: n × m matrix, defines the number of resources of each type currently allocated to each process.



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- ► *Available*: vector of length *m*, indicates the number of available resources of each type.
- ► Allocation: n × m matrix, defines the number of resources of each type currently allocated to each process.
- *Request*: $n \times m$ matrix, indicates the current request of each process.
 - If Request[i,j] = k, then P_i requesting k more instances of resource type R_j .



Detection Algorithm (1/2)

- ► 1. Let Work and Finish be vectors of length m and n, respectively. Initialize:
 - a. Work = Available
 - b. For $i = 1, 2, \dots, n$, if Allocationi $\neq 0$, then Finish[i] = false; otherwise, Finish[i] = true



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- ▶ 2. Find an index *i* such that both:
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- If no such i exists, go to step 4



Detection Algorithm (2/2)

 3. Work = Work + Allocation; Finish[i] = true go to step 2



Detection Algorithm (2/2)

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- ▶ 4. If Finish[i] == false, for some i, 1 ≤ i ≤ n, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked.



Detection Algorithm (2/2)

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- ▶ 4. If *Finish*[*i*] == *false*, for some *i*, 1 ≤ *i* ≤ *n*, then the system is in deadlock state. Moreover, if *Finish*[*i*] == *false*, then *P_i* is deadlocked.
- ► Algorithm requires an order of O(m × n²) operations to detect whether the system is in deadlocked state.



Detection Algorithm Example (1/2)

- ▶ 5 processes: P_0 through P_4
- ► 3 resource types:
 - A (7 instances), B (2 instances), and C (6 instances)
- ► Snapshot at time *T*₀

	Allocation	Request	Available
	ABC	A B C	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	211	$1 \ 0 \ 0$	
P_4	002	002	



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► Deadlock?



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▶ Deadlock? Sequence (P₀, P₂, P₃, P₁, P₄) will result in Finish[i] = true for all i



Detection Algorithm Example (2/2)

• P_2 requests an additional instance of type C

	Allocation	Request	Available		Request
	A B C	A B C	A B C		ABC
P_0	010	000	000	P_0	000
P_1	200	202		P_1	202
P_2	303	000		P_2	001
P_3	211	$1 \ 0 \ 0$		P_3	$1 \ 0 \ 0$
P_4	002	002		P_4	002



Detection Algorithm Example (2/2)

• P_2 requests an additional instance of type C

	Allocation	Request	Available		Request
	A B C	A B C	ABC		ABC
P_0	010	000	000	P_0	000
P_1	200	202		P_1	202
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P_3	211	$1 \ 0 \ 0$		$\bar{P_3}$	$1 \ 0 \ 0$
P_4	002	002		P_4	002

 Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes; requests



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P_0	010	000	000	P_0	000
P_1	200	202		P_1	202
P_2	303	000		P_2	001
P_3	211	$1 \ 0 \ 0$		$\bar{P_3}$	100
P_4	002	002		P_4	002

- Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes; requests
- Deadlock exists, consisting of processes P_1 , P_2 , P_3 , and P_4



Recovery From Deadlock



Recovery from Deadlock

- Process termination
- ► Resource preemption



► Abort all deadlocked processes.



- Abort all deadlocked processes.
- ► Abort one process at a time until the deadlock cycle is eliminated



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- In which order should we choose to abort?



- Abort all deadlocked processes.
- ► Abort one process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
 - 1. Priority of the process.
 - 2. How long process has computed, and how much longer to completion.
 - 3. Resources the process has used.
 - 4. Resources process needs to complete.
 - 5. How many processes will need to be terminated.



Resource Preemption

Selecting a victim: minimize cost



Resource Preemption

- Selecting a victim: minimize cost
- **•** Rollback: return to some safe state, restart process for that state.



Resource Preemption

- Selecting a victim: minimize cost
- ▶ Rollback: return to some safe state, restart process for that state.
- Starvation: same process may always be picked as victim, include number of rollback in cost factor.



Summary





- Deadlock
- Four simultaneous conditions: mutual exclusion, hold and wait, no preemption, circular wait



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- Deadlock prevention



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- Deadlock prevention
- ► Deadlock avoidance: resource-allocation algorithm, banker's algorithm
- Deadlock detection: Wait-for graph
- ► Deadlock recovery: process termination, resource preemption



Questions?

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